

Vertex Detection at the Muon Collider

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Vertex detector design concepts are fairly well advanced for the ILC (although we don't really know how to execute the designs).

Detailed studies by LCFI and others on B tagging

We can use these designs as a basis for Muon collider studies

Compare the machine environments – how must the designs change?

How do the changes affect the physics?

LC Vertex Physics Needs

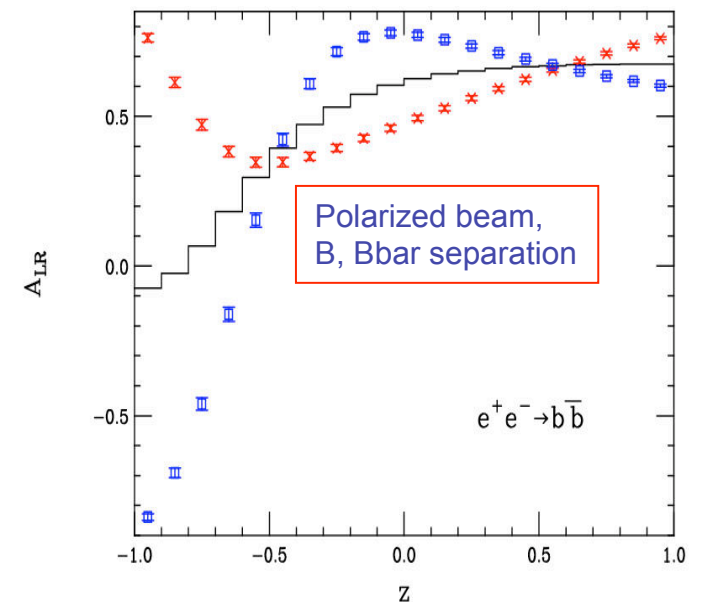
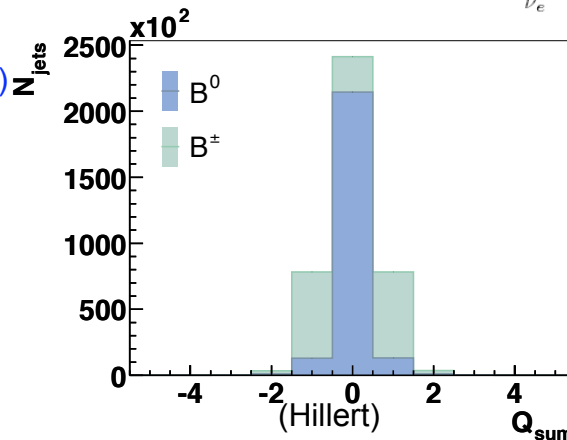
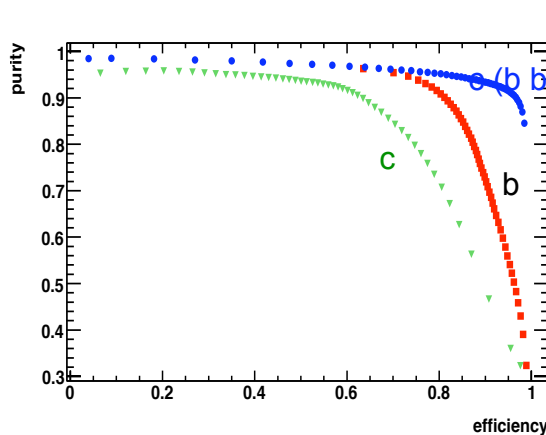
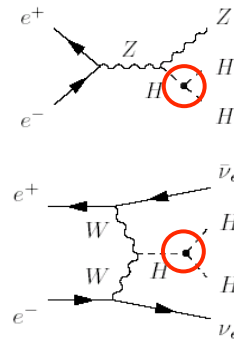
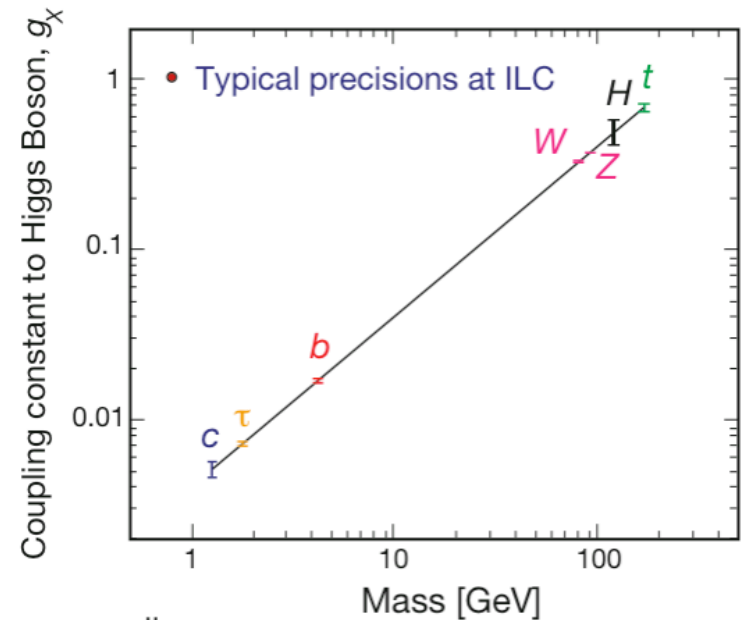
Lepton Collider is designed to do precision physics

- Higgs couplings
 - Require excellent separation of b/c/light quark vertices
- Higgs self coupling:

$$\mu^+\mu^- \rightarrow Z^0 H^0 H^0 \rightarrow qqbbbb$$

backgrounds: $tt \rightarrow b\bar{b}cscs, ZZZ, ZZH$

 - B quark ID within jets
- Forward-backward asymmetry ??
 - Flavor tagging
 - Vertex charge
 - Forward tracking

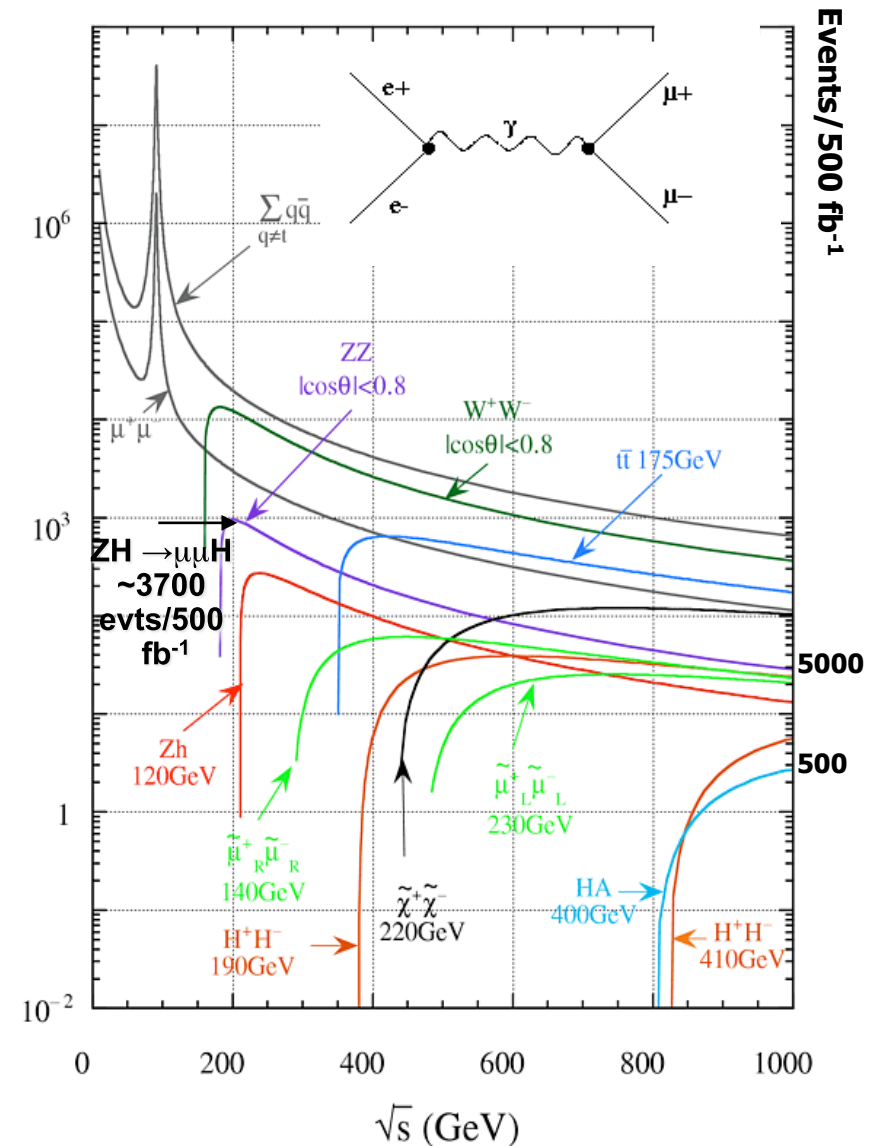


KK graviton exchange with jet-charge info
 $\sqrt{s} = 500 \text{ GeV}, \Lambda = 1.5 \text{ TeV}, 500 \text{ fb}^{-1}$
 (Hewett)

Physics Characteristics

- Machine design luminosity
 $L \sim 10^{34} \text{ cm}^{-2}\text{s}^{-1}$ ($\sqrt{s} = 2 \text{ TeV}$)
 - Cross sections are small
 - Hadronic event rate low
- Need to preserve signal
 - Need to preserve signal
- Need excellent particle identification
 - Discriminate W and Z in hadronic decay mode
 - Distinguish quarks from antiquarks

(Demarteau)



ILC Vertex Detector Goals vs μ collider

Basic goals are extrapolated from the SLD CCD vertex detector.

μ collider comments in red

- Excellent spacepoint precision (< 5 microns) ✓
- Superb impact parameter resolution ($5\mu\text{m} \oplus 10\mu\text{m}/(p \sin^{3/2}\theta)$) ??
 - Increased mass and larger inner radius will degrade resolution
- Transparency ($\sim 0.1\%$ X_0 per layer)
 - Mass associated with liquid cooling
 - Power density
 - Guess $\sim 0.4\%$
- Integration over < 150 bunch crossings ($45 \mu\text{sec}$) ✓
 - Closer to $10 \mu\text{s}$ for μ collider
- Moderately radiation hard
 - Significant radiation hardness
- Stand-alone pattern recognition (SiD)

Backgrounds

- Background considerations will likely dominate the design at the muon collider
 - Instantaneous backgrounds associated with beam crossing that increase occupancy
 - Radiation levels near the vertex detector that will generate radiation damage and dictate operating temperature and mechanical design
- Will force compromises with respect to ILC designs and eliminate some technologies

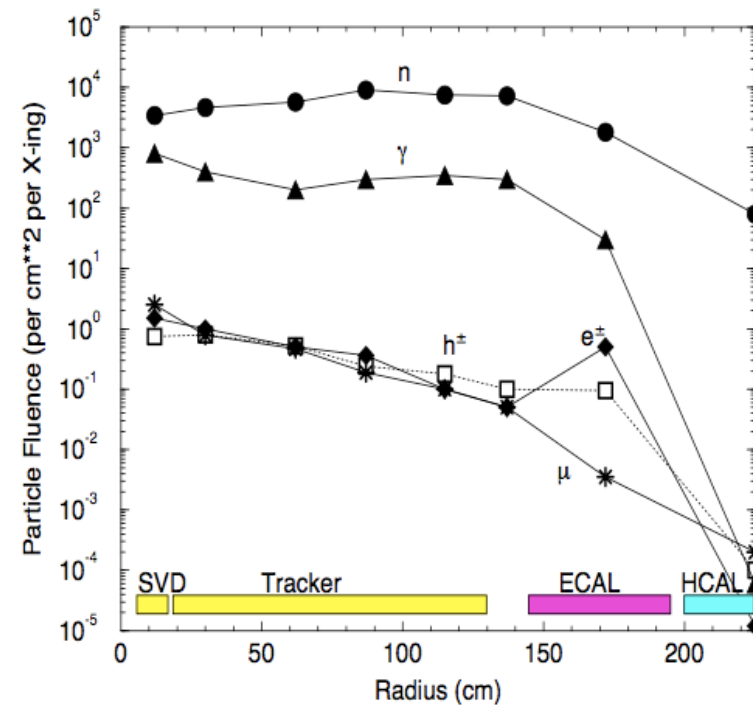
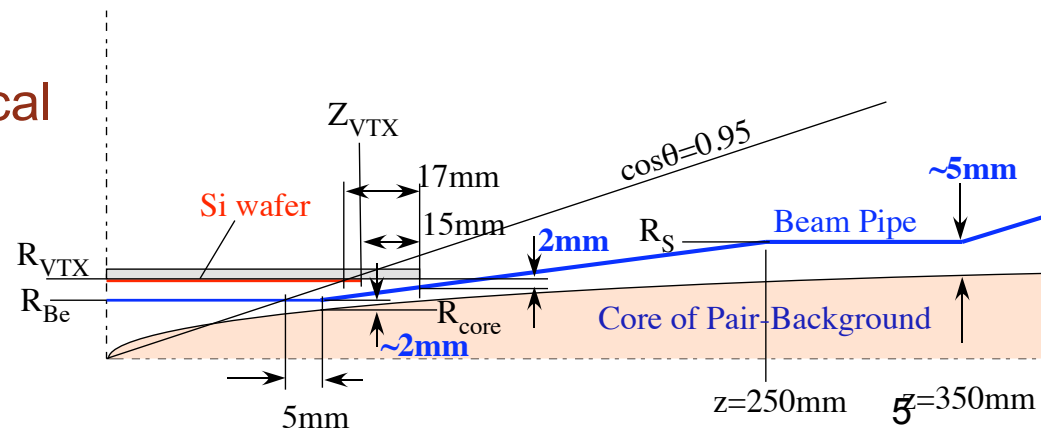
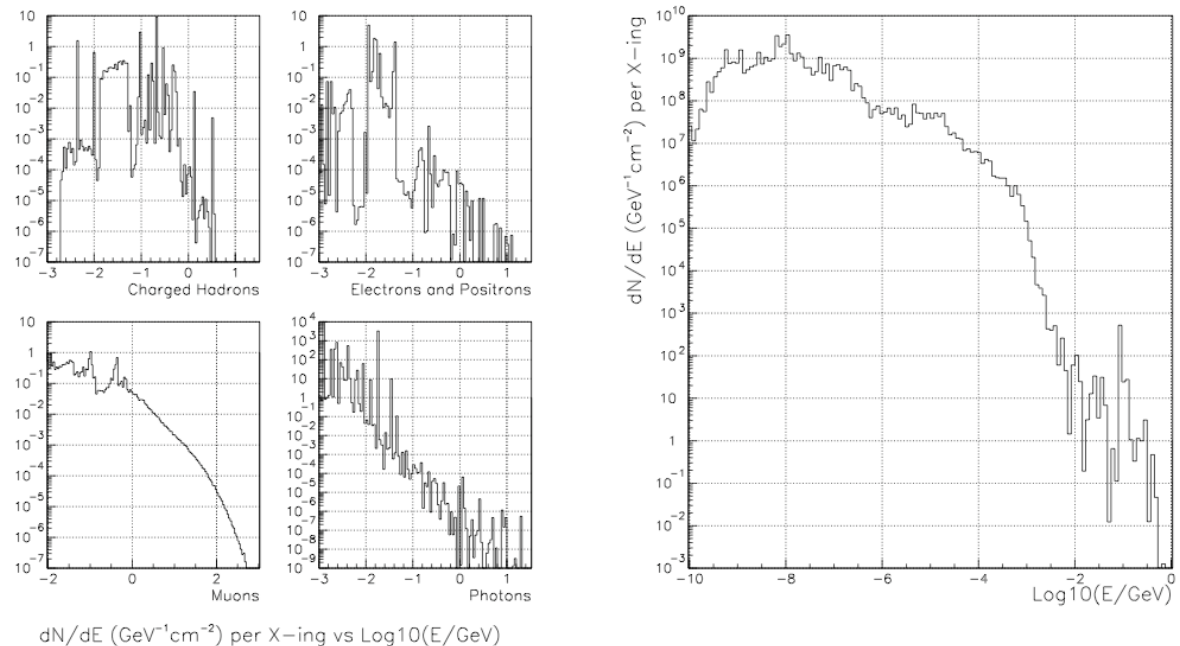
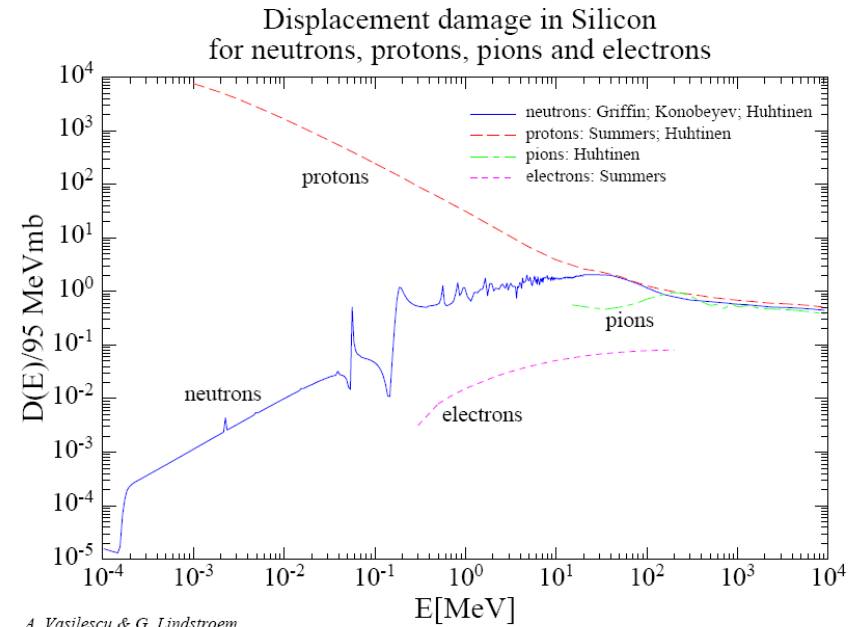


Figure 10. Particle flux radial distributions in a $\pm 1.2\text{m}$ detector region around the IP per $2 \times 2\text{ TeV } \mu^+ \mu^-$ bunch crossing.



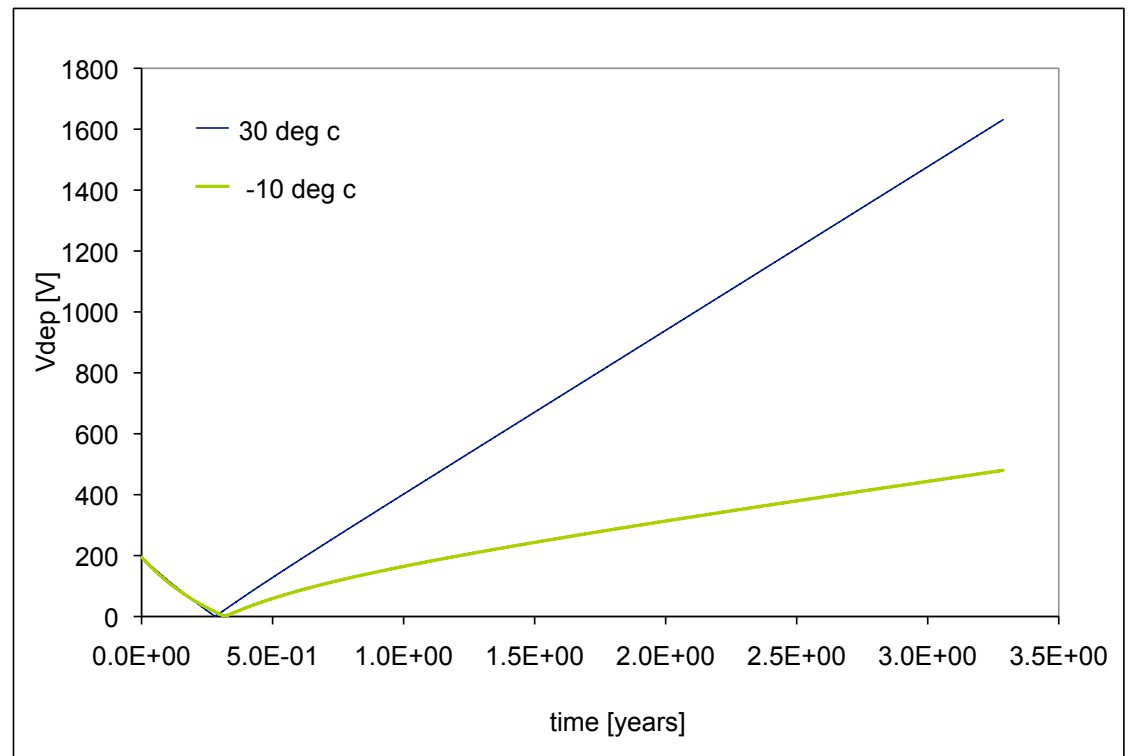
Backgrounds II

- Muon collider has a different radial distribution than a electron collider
 - More neutrons
 - Less disrupted beam
 - Upstream backgrounds
 - More complex shielding
- Particle composition is different:
 - need to calculate effective radiation damage factor vs radius for detailed folding of spectra
- Scale to non-ionizing energy loss
- Electrons cause much less displacement damage



Radiation Damage

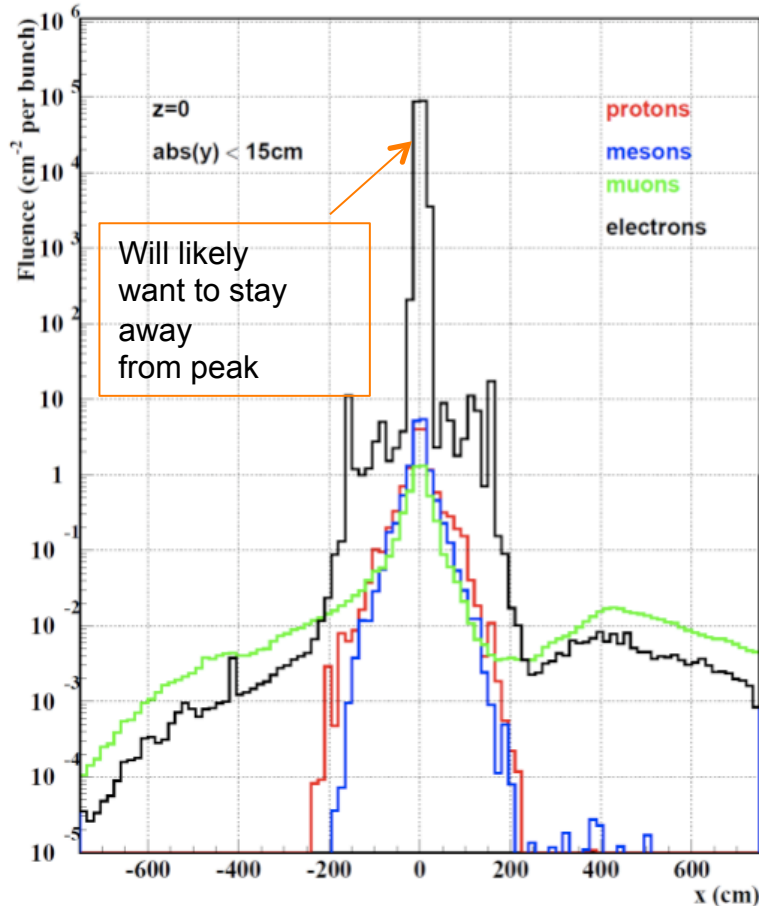
- Dominated by neutrons
- $1200/\text{cm}^2/\text{year}$ at 5 cm at 2x2 TeV
- $1200 \times 10^5/\text{sec} \times 3600\text{sec/hr} \times 500 \text{ hr/yr}$
 $\sim 2.6 \times 10^{14}/\text{year}$
 - Significant, still less than SLHC
 - Assume 200 micron thick, $V_{\text{dep}} \sim 200 \text{ V}$
 - Vertex (and tracker) need to be cooled to around 0 deg C
- This is a simple calculation that assumes 1 MeV neutrons and does not include other species
- Nikoli's latest – small nose calculation has higher fluences



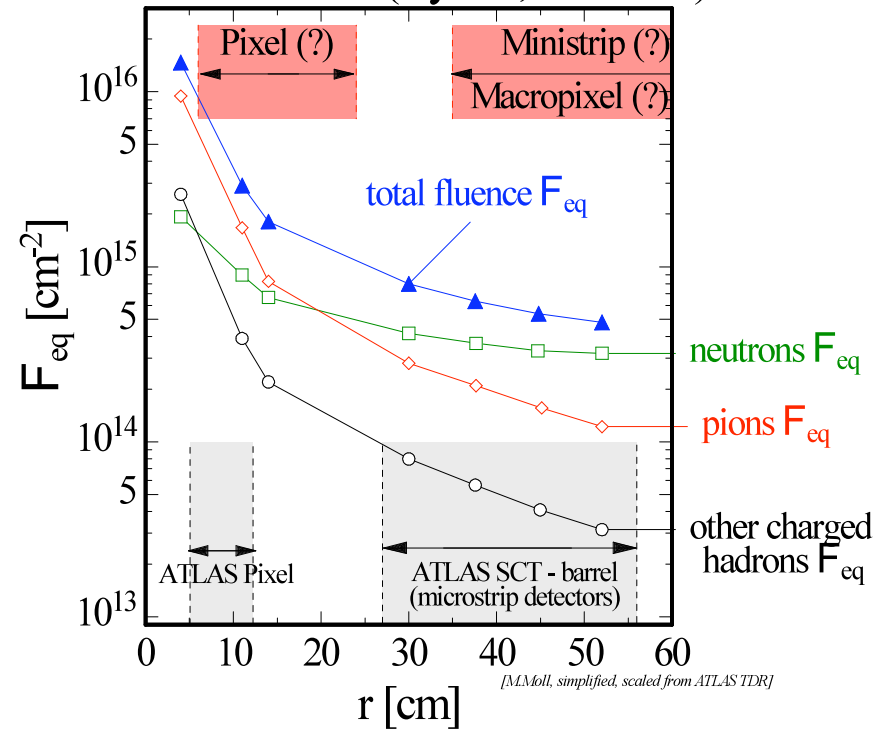
LHC and μ Coll

1 Mgy = 100 Mrad

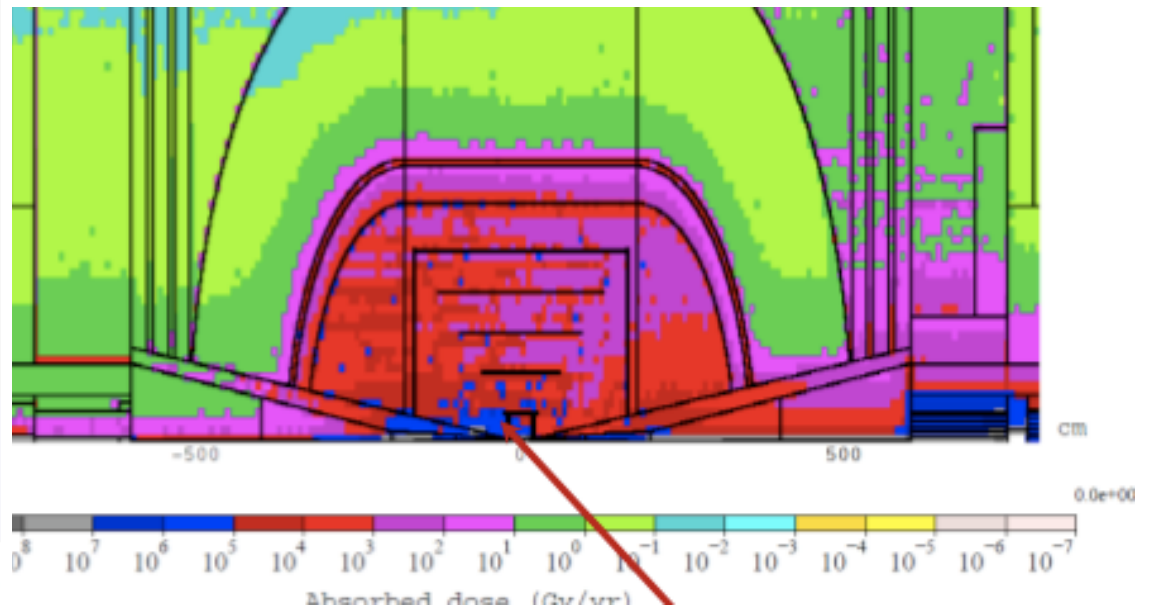
Need to scale all particle fluxes to NIEL damage, then compare to LHC



SUPER - LHC (5 years, 2500 fb^{-1})



(Mokhov)

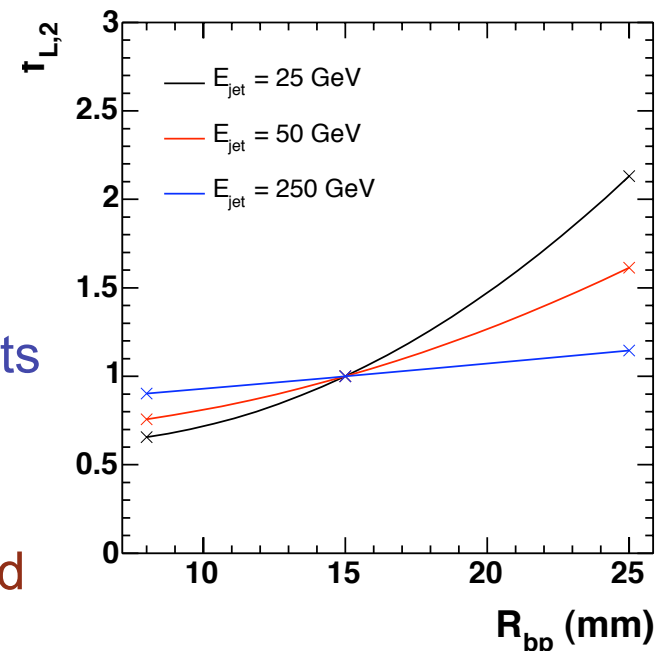


Vertex detector Geometry

Why do we worry so much about geometry

- Efficiency is important – the event rates are low
- Resolution really depends on inner radius and vertex detector mass
 - B-id efficiency and vertex charge ID depends strongly on resolution
 - Charm, B, and light quark separation for Higgs decay measurements
- Radiation levels determine cooling requirements
 - ILC detectors assume air cooling near RT
 - Heavily irradiated detectors will need to operate near -10 deg and may require liquid cooling – probably CO₂, which is more massive.

$$\sigma_z = \sigma_{hit} \frac{\sqrt{1 + \frac{r_i}{r_o}}}{1 - \frac{r_i}{r_o}}$$



Luminosity factor as a function of radius for processes requiring vertex charge for 2 jets

Performance Measures

- LCFI vertex charge ID performance measure for B decays in jet

$$\lambda_0 = 1 - \frac{\text{Neutral vertices reconstructed as neutral}}{\text{All generated neutral vertices}}$$

- Stringent – a single missed track can ruin the measurement
- Inner layer radius increase not accompanied by outer radius increase
- Should “scale” with IP resolution

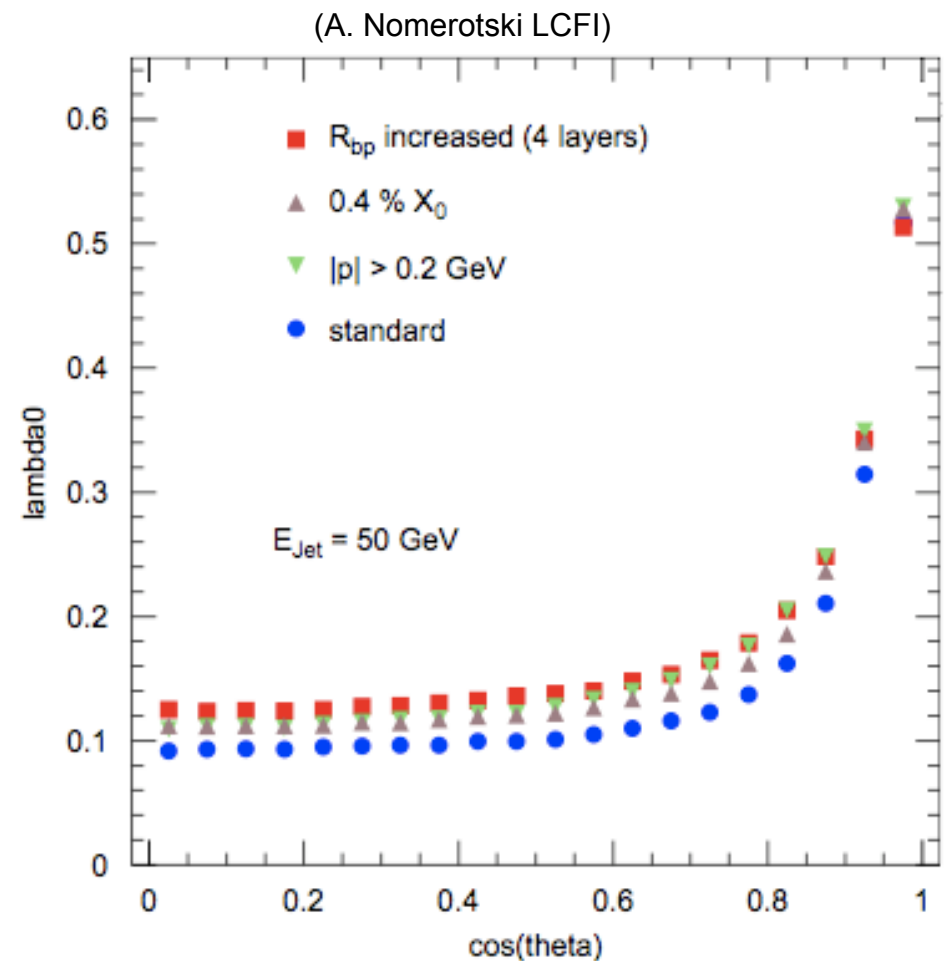


Fig. 4. Degradation in performance for minimal radius 25 mm, P_T cutoff in tracking 0.2 GeV and thickness per layer 0.4% X_0 .

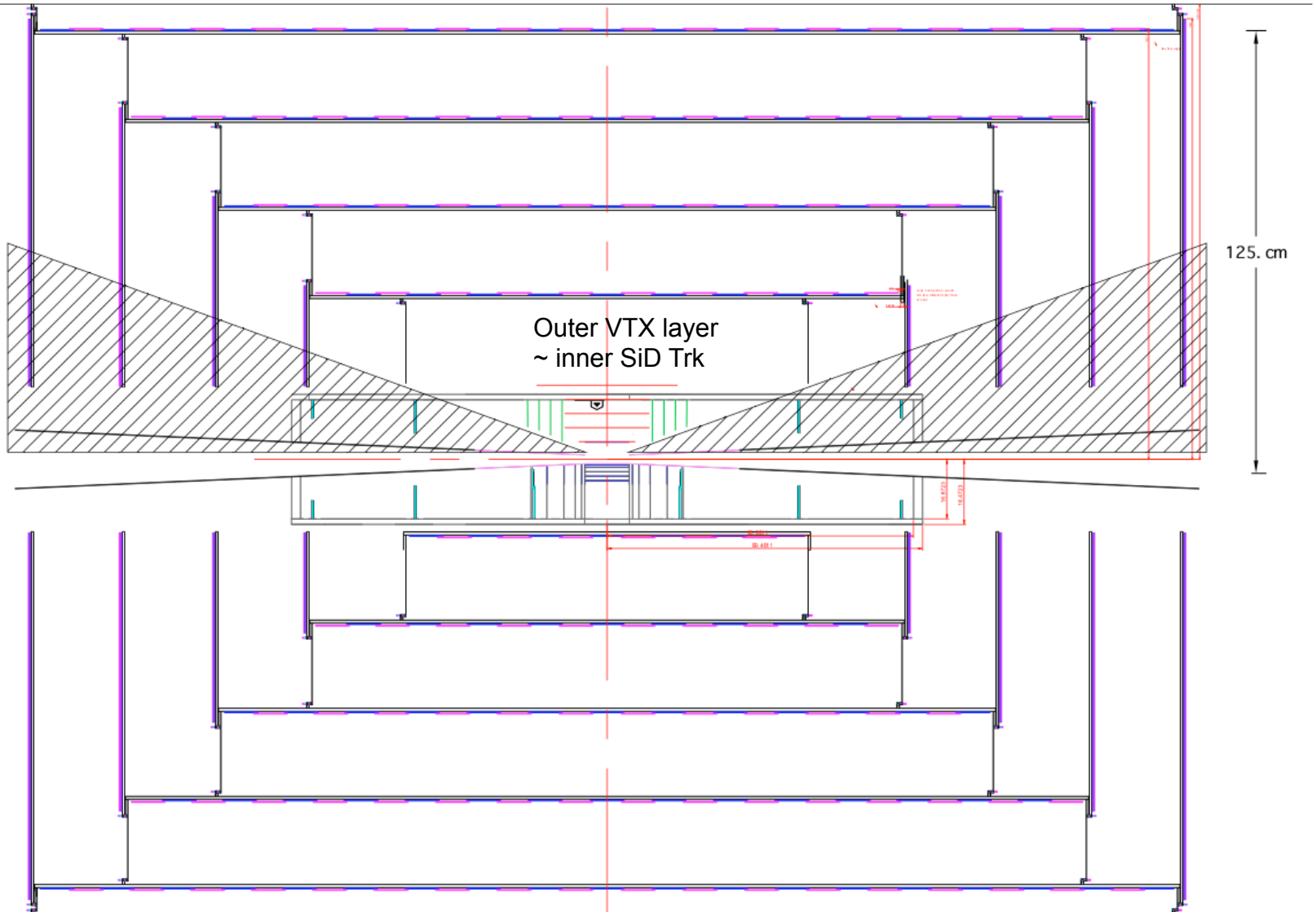
SID MuColl Frankfurt

20 deg
cones

Outer VTX layer
~ inner SiD Trk

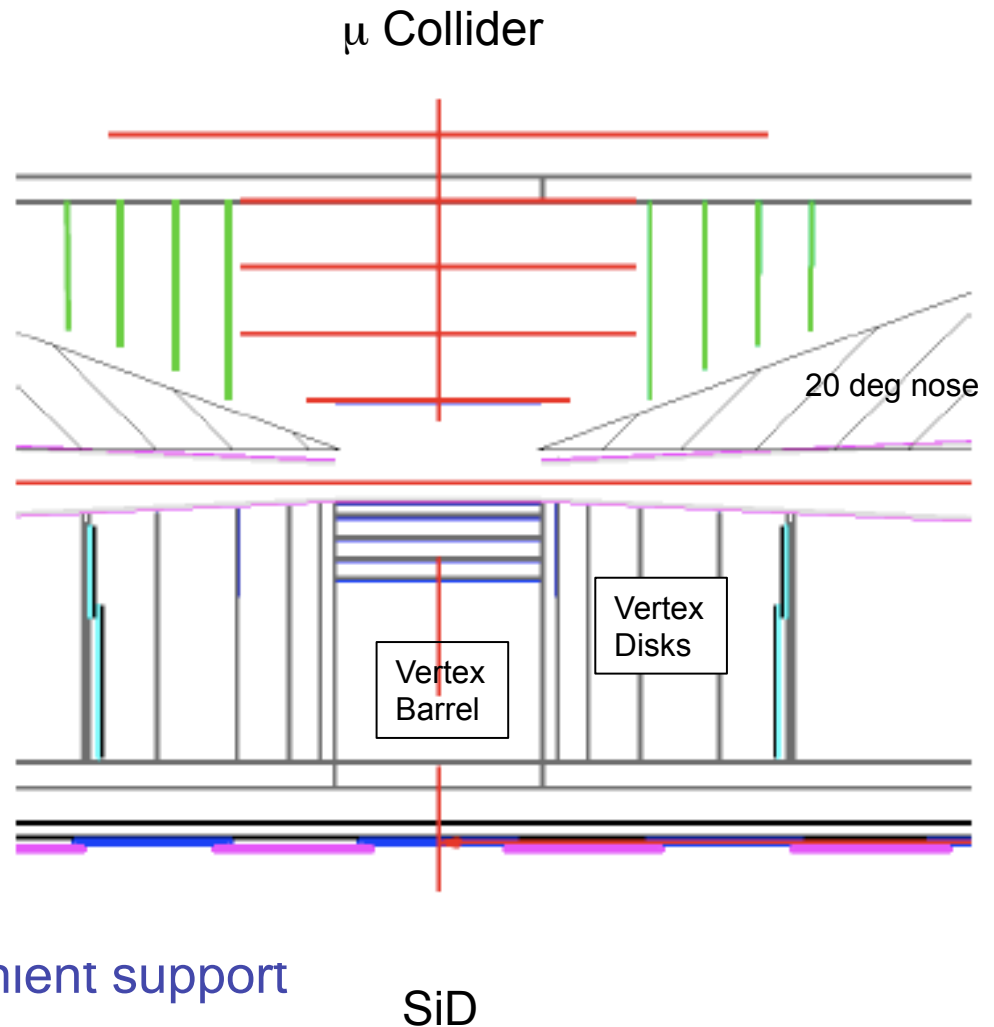
125. cm

Ronald



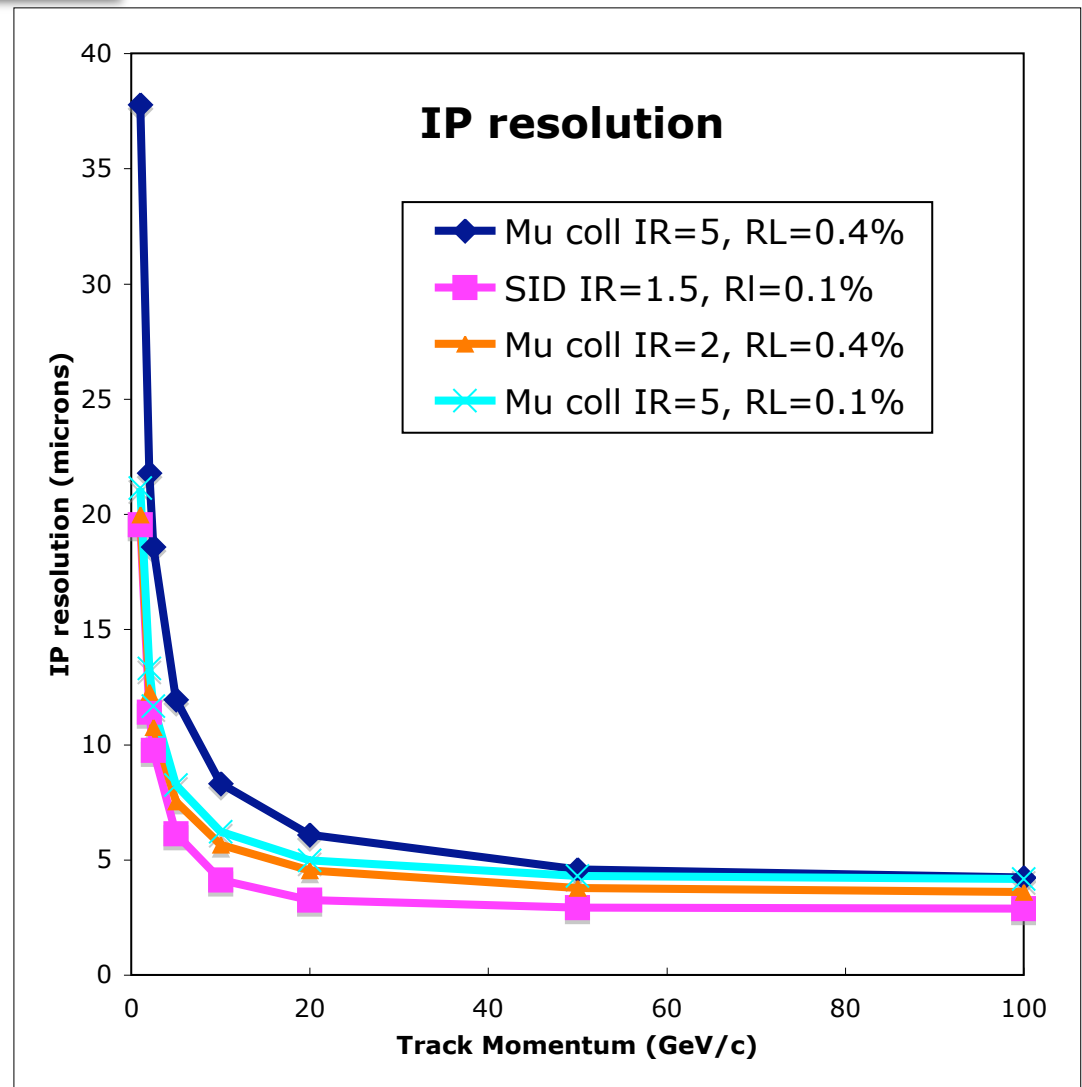
Design Features

- ILC
 - Outer radius ~ 6 cm
 - Barrel length ~ 14 cm
 - Ladder widths 1-2 cm
 - Disks to cover forward reg
- Muon Collider
 - Inner radius ~ 5 cm
 - Outer radius ~ 15- 20 cm
- Caveat – this is *NOT* a real design – just a sketch of how designs might evolve
- The nose does provide a convenient support and service routing region
- Could also serve as heat sink?



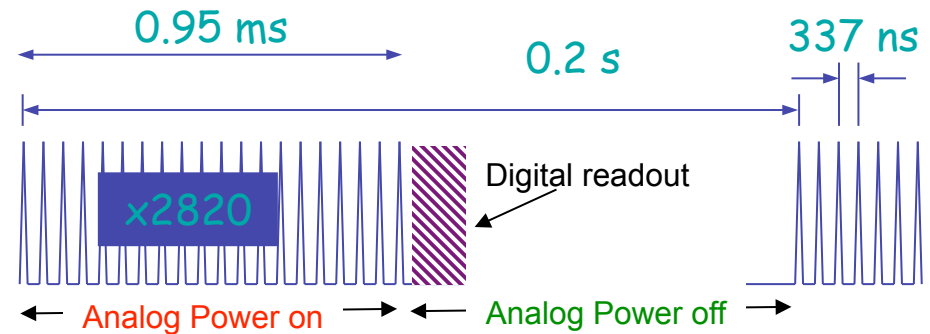
IP Resolution

- Use track fit spreadsheet to estimate degradation of resolution
 - Based on SiD design
 - 5 micron vertex and 12 micron track hit resolution
 - Radii of (1.5→6 cm) go to (5→20 cm) or (2→20 cm)
 - 0.1% RL/layer → 0.4%
- At most x 2 worse
- Keeping constant r_{in}/r_{out} important
- Can trade radius for RL



Beam structure and Time Resolution

- ILC – 1 ms train every 0.2 sec
- ILC - No trigger - read all hits
- Muon collider short bunches every 10-20 μs
 - 1 event every 90 seconds at 10^{34} at 1.5 TeV
 - This will probably be a triggered system
 - 10^6 less data flow
 - Can an efficient trigger be formed
 - Long FE integration time \rightarrow lower FE power
 - Low digital and data transmission power
 - Latency is probably modest (triggers would not be complex)
- Time is power (FE current, more clock cycles, power = $f \times \Delta V \times C \dots$)



Material

- To achieve ILC goals we must improve RL/layer over LHC by $\sim 20 \times$
- For muon collider we need to deal with
 - Liquid cooling
 - Increased data load?
 - Increased power
 -
- Detector will be thinned to 50-100 microns
 - Less mass and more rad hard

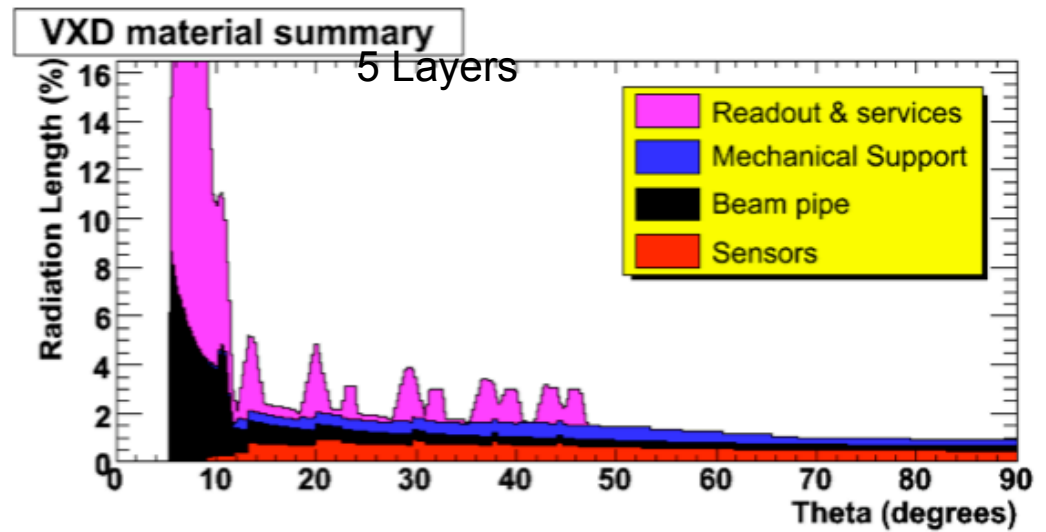
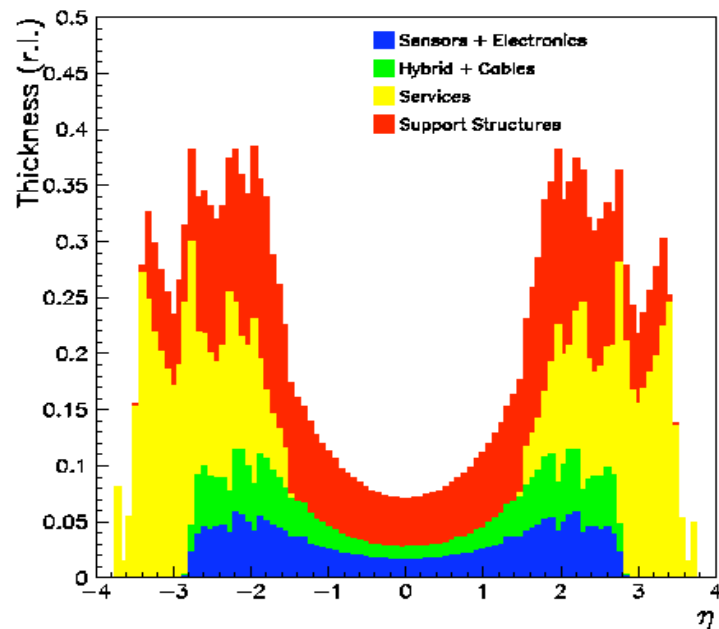


Figure 33 VXD hit pattern and material summary as a function of polar angle.

Noise and Power

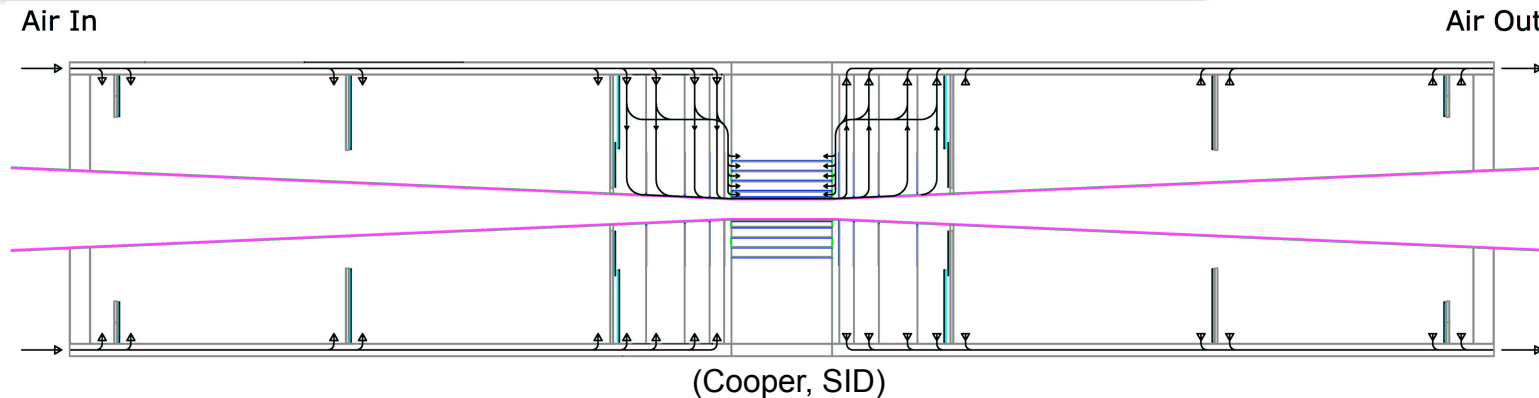
For pixel amplifier-based devices the FE amplifier usually dominates power consumption:

- Series white noise:

$$ENC^2 = (C_{\text{det}} + C_{\text{gate}})^2 \frac{a_1 \gamma 2kT}{g_m t_s}$$

- Noise scales as C and 1/sqrt[transductance (g_m)]
- Pixel front end transistors will operate in weak inversion - where g_m is independent of device geometry and $\sim(I_d/nV_T)$.
- Need $< 200 \mu\text{W}/\text{mm}^2$
- Acceptable low current operation ($<1 \mu\text{A}$) requires long shaping and/or low node capacitance
 - For $t_s = 1000\text{ns}$, $I_d=0.1 \mu\text{A}$ $C_d \sim 100 \text{ff}$ noise $\sim 35\text{-}50 \text{ e}$
 - $\sim 10 \text{ ff}$ should be achievable in SOI devices, 20-40 in MAPS
 - FE power $\sim 200 \mu\text{W}/\text{mm}^2$ with 20 micron pixels – but this does not count any other parts of the circuit – pretty hard to achieve air cooling.

Air Cooling



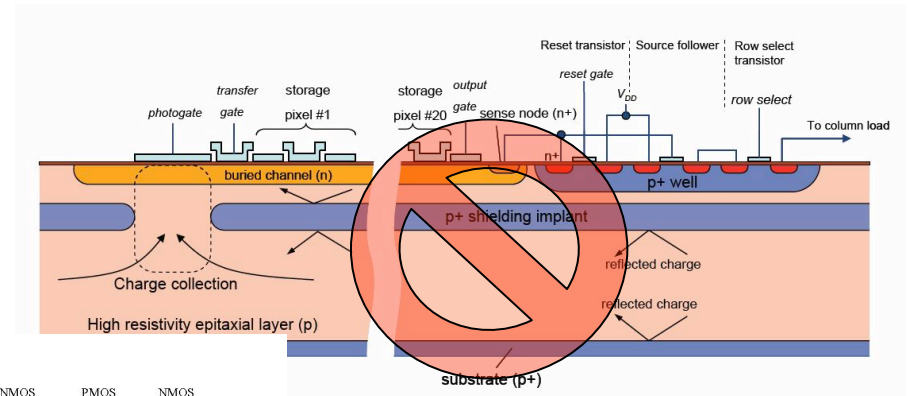
- Air cooling in ILC is needed to keep mass to a minimum (remember 0.1%)
 - implies a limit on power dissipation
- Estimate by requiring laminar flow through available apertures
 - This sets total mass flow – other quantities follow
- For SiD design
 - Use the outer support CF cylinder as manifold (15mm Δr)
 - Maintain laminar flow ($Re_{max} = 1800$).
 - Total disk (30W) + barrel (20W) power = 50W *average*
 - For SiD $\sim 131 \mu W/mm^2$.
 - Max $\Delta T \sim 8$ deg

Power Distribution

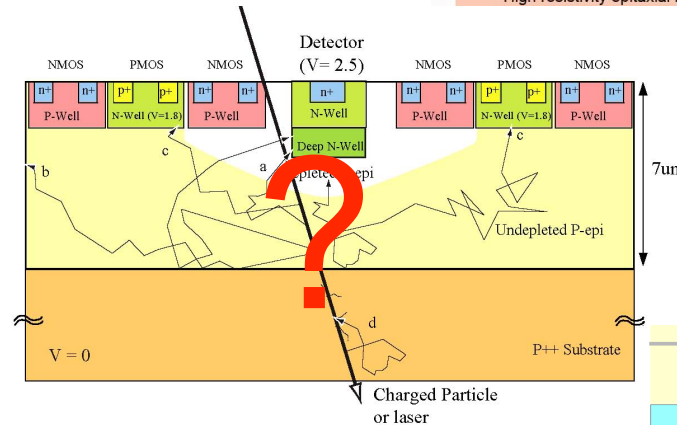
- Power goals in ILC are “met” using power pulsing
 - Duty factor $\sim 1/200$ assume 1/100 power savings
 - Peak and average power are both crucial issues for the vertex detector
 - Power pulsing for FE chips - just turn power on during 0.95/200 ms
 - Maximum duty factor ~ 200 , assume ~ 100 may be practical
2000 W \Rightarrow 20 W (average)
 - But I_{peak} is still the same - 2000A if we saturate the 20W limit
 - High peak currents \Rightarrow more conductor to limit IR drop \Rightarrow Mass
 - Serial powering, DC-DC conversion can lower instantaneous current
- The μ collider beam structure does not allow for power pulsing
 - Probably need liquid cooling
 - More than 0.1% RL mass

Sensor Design

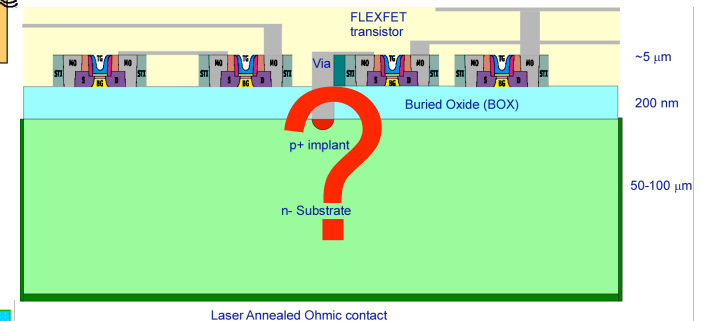
- CCDs
 - Readout too slow
- CMOS Active Pixels
 - Possible, radiation hardness?
- SOI
 - Possible, radiation hardness?
- 3D
 - Yes
- DEPFET
 - Probably too slow



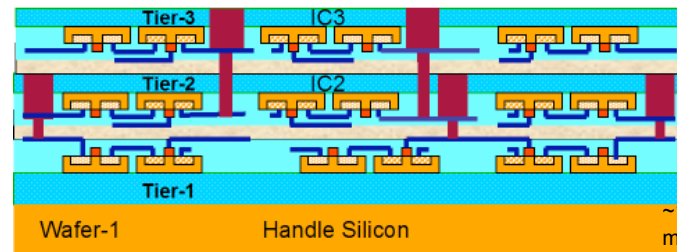
CCD



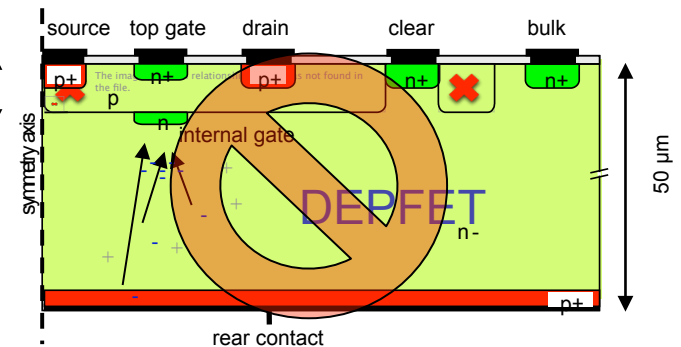
CMOS Active Pixels



SOI



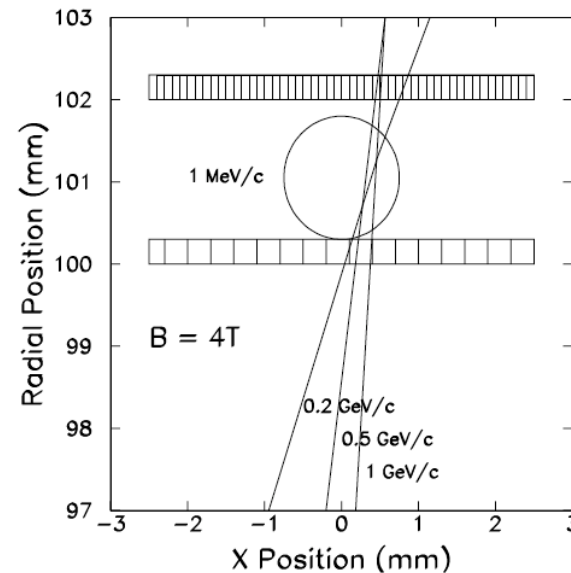
3D



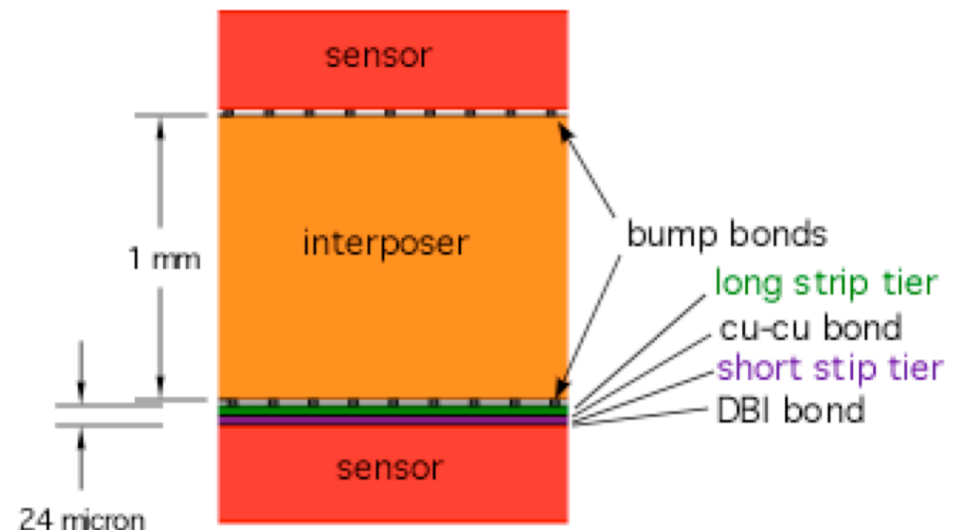
DEPFET

Sensors

- 20th Century studies assumed 300 μm square pixels
- ILC studies assume $\sim 20 \mu\text{m}$ square pixels x 225 less occupancy/pixel
- It is likely that these smaller pixelated devices will provide sufficient resolution for good pattern recognition.
- But other techniques can be used to reduce occupancy based on inter-layer correlations
- This technology is being developed for CMS upgrade



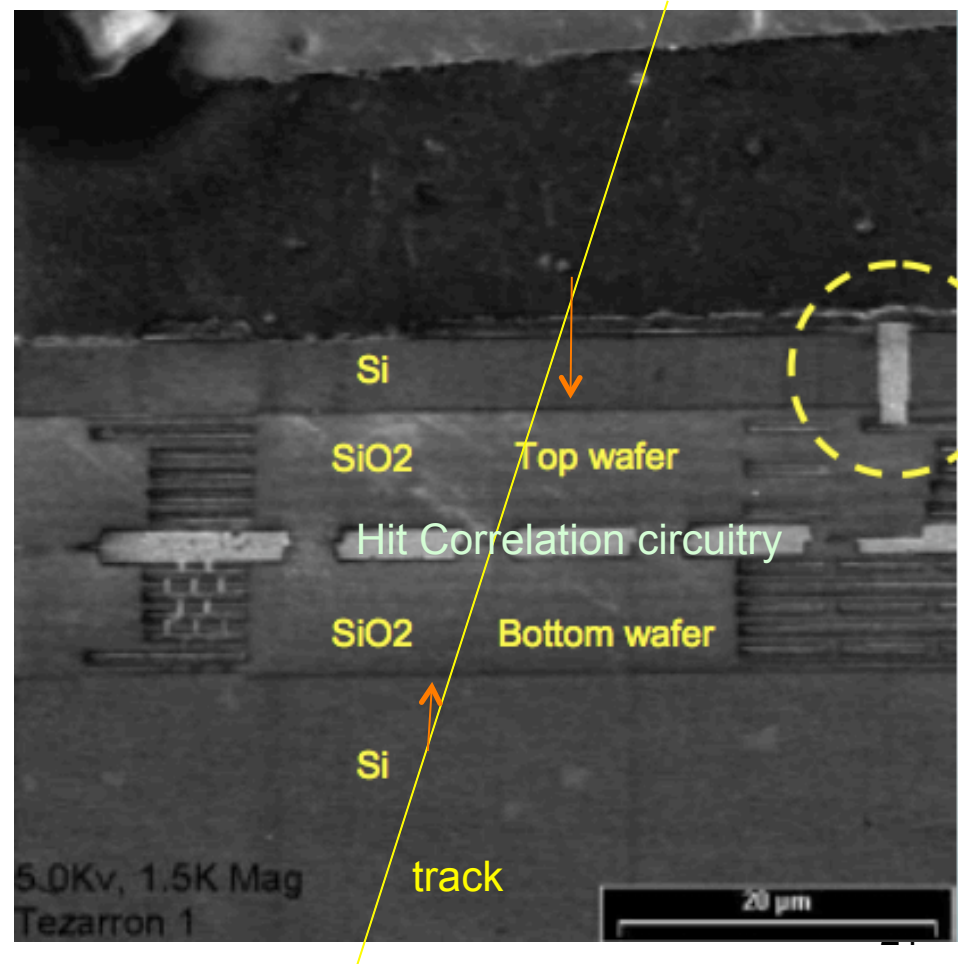
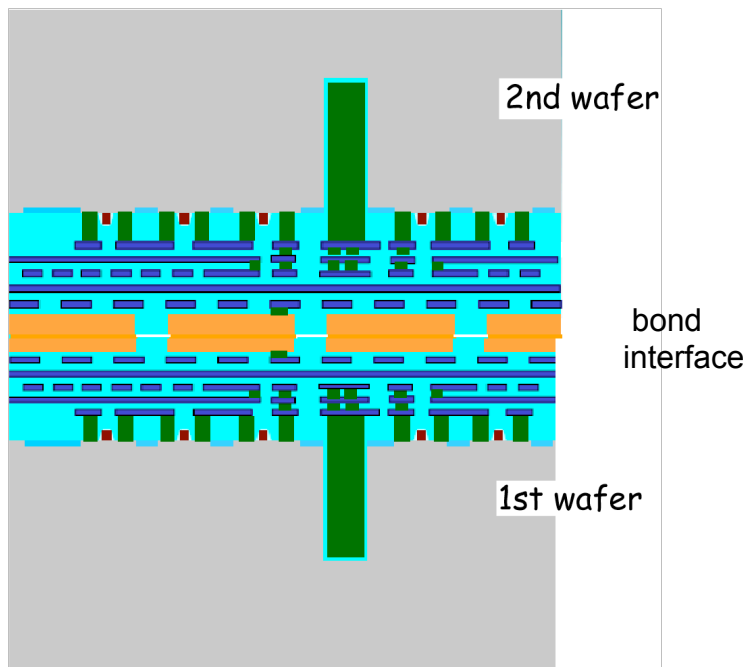
1999 μCol
Track
correlation
module



2009 Track trigger module for CMS Phase II
Based on 3D electronics

False hit rejection

- Random false hits can be rejected with minimal material and modest power penalty using 3D bonded monolithic active pixel ICs
- We could almost do this now



Conclusions

- A few initial comments:
 - Both vertex and tracker will need to be cooled below 0 deg C
 - Vertex detector inner and outer radii will increase over ILC
 - Increased mass/layer due to water cooling
- Loss of forward region due to collimation “nose”
 - Can A_{fb} measurements be retained?
 - Can the nose be modified?
 - Can it be used for cooling and services?
- Too early for real conclusions but it appears that excellent tracking and vertexing can be retained with moderate effective luminosity loss.

